

Breaker Failure Relay, Control Relay, Data Recorder



# **Major Features and Benefits**

### ► Circuit Breaker Failure Detection:

- > Failure while tripping fault conditions
- > Failure while tripping load conditions
- Failure to close (pole disagreement detection)
- Failure while open (breaker pole flashover detection)
- Failure to complete a trip or close (resistors still inserted)
- > Loss-of-dielectric pressure

### ► Control Logic:

- Motor-Operated Disconnect (MOD) trip and power circuit breaker isolation security logic
- Retripping (instantaneous and timedelayed)
- Point-on-Wave (POW) breaker control functions
- > Synchronism checking close logic
- > Trapped charge polarity detection

### ► Data Recording:

Event report provides 8 seconds of analog fault data and digital oscillography data at 64 samples per cycle

- 512 Sequential Event Recorder (SER) reports (inputs, outputs, and relay elements)
- > 512 breaker operation events
- Six voltage measurements
- > Three current measurements
- > Additional Features:
  - > Multiple I/O configurations
  - SELOGIC<sup>®</sup> control equations: Modify default schemes Complete custom applications Design a recloser
  - Programmable targets for testing
  - Detailed metering
  - > Three EIA-232 serial ports
  - ➤ EIA-485 serial port
  - Front-panel display: Setting and monitoring functions
  - Automatic self-tests
  - > Clock synchronization input, IRIG-B
  - Optional DNP3 Level 2 Slave

# **Functional Overview**



Figure 1 Functional Diagram

The SEL-352 relay is a single- or three-pole breaker failure detection, breaker control, and data recording device. Each of the protection schemes is implemented in SELOGIC control equations, giving relay engineers unparalleled flexibility in adapting the relay to their needs. The relay provides classical overcurrent-based breaker failure protection for a wide variety of breaker arrangements. Additionally, protection is provided for circuit breaker trip and close resistors, for current through an open breaker, and for breaker flashover.

Logic to control the closing and opening of the circuit breaker is also included. Additional features include metering, sequence-of-event reporting, digital fault recording, remote setting capabilities, breaker operating time monitors, energy interruption monitors, and breaker resistor thermal protection. Simple hardware design and efficient digital signal processing ensure reliability. Extensive self-testing and communication capabilities enhance availability.

*Figure 2* shows a single-phase diagram of the ac connections. All nine connections are not required for most relay functions.



Figure 2 Single-Phase Diagram of AC Inputs to the Relay

### **Circuit Breaker Failure Detection**

The SEL-352 has five fault current-driven breaker failure detection schemes, including one specifically designed for ring-bus or breaker-and-a-half applications. Tailor the relay to your circuit breaker failure detection requirements by selecting the most appropriate scheme or use SELOGIC control equations to implement your own scheme.

The relay detects failures to interrupt fault, load, or linecharging current. It also detects failure of breaker poles to complete a close sequence and can detect open breaker flashover failures. If trip or close resistors remain in service after an operation, the relay detects this failure using a thermal model.

Independent phase current detectors, protection logic, and timers make the relay easy to apply on both simple systems and more complicated breaker arrangements such as single-pole trip installations.

The SEL-352 stores summaries of the last 512 breaker operations in nonvolatile memory. Event type, maximum current, mechanical and electrical operating times, and breaker energy are stored along with the date and time of operation. Using this breaker history, you can monitor breaker wear and effectively schedule routine breaker maintenance.

When a motor-operated disconnect switch (MOD) is used with the protected breaker, the SEL-352 can trip the MOD to isolate the failed breaker when phase current drops below a settable value. When a MOD is not installed, use the MOD logic to indicate a "Safe to Disconnect" condition to personnel.

The relay also includes SELOGIC control equations, which allow you to configure the programmable outputs to operate when any of the protective elements pick up. You can implement complete application-specific protective schemes with a minimum of wiring and panel space. SELOGIC control equations also simplify relay testing.

### **Control Logic**

Control logic provides flexibility for closing, opening, and tripping. For minimal breaker wear, the SEL-352 can be used to close the breaker at an optimum time. Close using a simple pole staggered close or utilize complete control by monitoring synchronism, trapped charge polarity, and zero crossings. Use controlled breaker opening in the SEL-352-2 and SEL-352-3 for synchronizing the maximum breaker contact separation to peak or zero voltage crossings to help reduce the occurrence of re-strike in reactive loads. Utilize ambient temperature and dc control voltage monitoring to compensate for variations in breaker close and opening times in the controlled opening and closing schemes. Control breaker tripping through lockout and reset conditions, instantaneous retripping, and time-delayed retripping.

Use the flexible SELOGIC control equations to create your own recloser, implement manual closing supervision, and /or change existing control logic to meet your needs.

#### 4

### Data Recording

A wide range of user-selectable events trigger the sequence-of-events recording (SER) and digital fault recording (DFR) functions, including any input or output assertion. Breaker Failure Trip (86BFT) output assertion automatically generates a DFR record, and you can set the relay to trigger an event for OPEN, CLOSE, or TRIP input assertions. This ensures a record of every normal circuit breaker operation as well as every circuit breaker failure.

The recorded data contain all information needed to determine the cause of relay and breaker operations. The data collected include current through the circuit breaker, voltage on both sides of the circuit breaker, input, output, and relay element data. Parameters such as event type, relay response time, circuit breaker operation time, currents, voltages, and breaker power dissipation appear directly in the breaker monitor report or can be calculated from the data stored. All event reports are time-tagged by a self-contained clock/calendar.

### **Additional Features**

Additional features make the SEL-352 reliable and economical. The communication functions provide remote and local examination of a wide range of data, including the voltages and currents presented to the instrument, relay settings, history of events, breaker alarms, sequence-of-events, and self-test status data. You can enter and modify relay settings remotely; you can also control all outputs via the communications channel.

A three-level password scheme protects settings and circuit breaker control. The SEL-352 monitors password execution and closes the ALARM contact output to indicate possible unauthorized access. The relay requires no special communications software. Access the relay with a dumb terminal, printing terminal, or computer with serial port and terminal emulation software. The SEL-5010 Relay Assistant is also available for communication and settings database management.

# **Circuit Breaker Failure Detection**

### **Protection Overview**

The SEL-352 provides protection for several circuit breaker failure modes:

- ► Failure to clear a fault (five available schemes)
- ► Failure to trip during load conditions (two available schemes)
- Failure to complete trip sequence due to trip resistor(s) remaining inserted
- ► Failure to complete close sequence due to close resistor(s) remaining inserted
- ► Failure to close: pole disagreement detection
- ► Failure while open: breaker pole flashover detection
- ► Loss of dielectric pressure

### **Protection While Tripping Fault Current**

The SEL-352 provides five different protection schemes to detect the failure of the circuit breaker to clear a fault. While the schemes share elements and timers, each is independent. You may enable only one protection scheme at a time. The SEL-352 applies the single chosen scheme to all three breaker poles. The SEL-352 provides instantaneous overcurrent elements (50FT) with fast reset times, even in the presence of subsidence current after the breaker opens.

In ring-bus and breaker-and-a-half installations, two circuit breakers must operate to interrupt line current. Current distribution between the two breakers is unknown until the first breaker opens. This causes an uncertainty with respect to the timing of 50FT overcurrent element assertion. This uncertainty is not present in a single breaker arrangement.

Timing uncertainty is accounted for in the SEL-352 breaker failure detection schemes intended for these complex bus/breaker arrangements. The SEL-352 is intended to monitor a single breaker, regardless of the bus/breaker arrangement. In breaker-and-a-half and ring-bus arrangements, you must use an independent breaker failure relay for each breaker.

An overview of the five protection schemes is shown below.

#### Scheme 1: Protection for Simple and Complex Arrangements

In this scheme, the breaker failure timer starts independently from 50FT assertion. This independence allows scheme usage in bus configurations where the 50FT element may assert after trip input assertion, such as ring-bus and breaker-and-a-half bus arrangements.

Logic latches in the trip signal so that trip signal dropout does not affect the breaker protection scheme.

# Scheme 2: Basic Protection for Simple Arrangements

In a single breaker arrangement, fault current causes 50FT assertion immediately after fault inception and just prior to trip input assertion. In Scheme 2, the breaker

failure timer does not start until the trip input and 50FT element are asserted. This allows definite, predictable scheme timing in single-breaker configurations.

#### Scheme 3: Simple Arrangement Protection Independent of 50FT Reset Time

Scheme 3 is intended for a single breaker arrangement. When a fault occurs, 50FT asserts. The line protective relay asserts the SEL-352 trip input, and the breaker failure timer starts. If the trip input and 50FT are asserted until the timer expires, a breaker failure condition is declared.

In Scheme 3, the trip input must remain asserted while current flows in the protected breaker. Scheme 3 resets when either the trip input deasserts or the 50FT element drops out.

# Scheme 4: Sensitive Scheme for Simple or Complex Arrangements

When the SEL-352 trip input is asserted, the breaker failure pickup timer starts. The trip input is latched and may be deasserted after a single quarter-cycle assertion. The breaker failure timer output asserts a settable time after a trip input asserts and remains asserted for a settable dropout time. A breaker failure condition is declared if the timer output is high and the phase 50FT element is asserted.

#### Scheme 5: Scheme for Simple or Complex Arrangements

When the trip input is asserted, the breaker failure timer starts. If 50FT is asserted when the timer expires, a breaker failure condition is declared. If the trip input deasserts or 50FT drops out before the timer expires, the logic resets.

This scheme is similar to Scheme 3 because the trip input must remain asserted while current still flows in the protected breaker.

### Protection While Tripping Load or Line-Charging Current

Two different schemes detect breaker failures when tripping the breaker under load or line charging current conditions. While the schemes share elements and timers, each is independent. You may enable only one protection scheme at a time or customize the logic.

Both schemes require that the breaker is closed, and the relay received a trip input. The difference between the two schemes is how they determine a closed breaker condition. Scheme 1 determines a closed breaker condition by comparing the phase current with the 50LD setting. Because this logic is very sensitive, the trip input must be asserted for two consecutive quarter-cycles before this logic acknowledges the input.

In some applications, current through the closed breaker may be below the minimum setting of the 50LD element. Scheme 2 uses the same logic as Scheme 1 but adds the 52A monitoring condition as an additional means for determining an open or closed breaker.

# Thermal Protection of Close and Trip Resistors

If the protected breaker is equipped with trip and close resistors and three-phase potentials are available on both sides of the breaker, you can use the SEL-352 thermal protective elements to protect breaker resistors. Occasionally, a trip or close resistor can be left in service following a breaker operation. The SEL-352 can detect that condition, model the energy accumulated in the resistor, and trip the protected breaker or 86 lockout relay when resistor energy reaches a preset level.

A "Close Resistor Thermal Failure" or "Trip Resistor Thermal Failure" is declared when any close or trip resistor thermal model has reached the failure energy level and current is flowing in the hot resistor phase.

The relay models cooling of the breaker resistors using settable time constants. The thermal elements do not drop out until the resistor thermal models have cooled below the element thresholds. This function helps prevent hot resistors from being returned to service.

### Voltage Nulling

The thermal protection and flashover protection both require a measurement of the transient voltage difference across the circuit breaker. Voltage nulling logic removes the steady state voltage difference that appears across the breaker. With the steady state voltage difference nulled from the voltage difference measurement, any difference is due to transient conditions.

# Protection for Current Through an Open Breaker (Flashover)

Two schemes to detect circuit breaker flashover are provided. While the schemes share elements and timers, each is independent. You may enable only one flashover detection scheme at a time, or you can customize the logic.

Scheme 1 uses voltage across the circuit breaker and the current through the breaker to detect flashover. Scheme 2 uses a single set of voltages on one side of the breaker, the current through the breaker, and the breaker monitor input to detect flashover.

### **Protection for Failure to Close**

The SEL-352 includes logic which detects a failure of one or two breaker poles to close. Because the logic operates based on current flowing in the breaker poles, protection is not dependent upon the operation of auxiliary contacts. Thus, this logic is not subject to misoperation due to mechanical failure in the breaker or contacts.

# **Control Logic**

The SEL-352 provides the following control logic:

- ► Staggered Closing
- ► Point-on-Wave Closing, which includes:
  - > Synchronism Checking
  - ➤ Zero-Crossing Detection
  - > Trapped Charge Polarity Detection
  - High-Resolution Controlled Close Output Timers
  - Ambient Temperature Compensation (SEL-352-2 and SEL-352-3)
  - DC Control Voltage Compensation (SEL-352-3)
- ► Point-on-Wave Opening, which includes:
  - ➤ Zero-Crossing Detection
  - High-Resolution Controlled Open Output Timers
  - Ambient Temperature Compensation (SEL-352-2 and SEL-352-3)
  - DC Control Voltage Compensation (SEL-352-3)
- ► Circuit Breaker Retrip Logic
- ► Breaker Failure Trip and Reset Logic

### **Staggered Close**

Scheme 1 of the controlled close logic is a staggered close scheme that allows the user to close each pole of a circuit breaker pole at a settable time. The pickup time for each phase timer is settable to allow the user to select the delay between each phase.

### **Point-on-Wave Close**

The second closing scheme that the SEL-352 provides is a point-on-wave close. Scheme 2 controls at what point on the voltage waveform the circuit breaker closes. The point-on-wave close logic is designed to provide a closing scheme that minimizes breaker wear and system impact when the breaker closes. Point-on-wave closing includes synchronism checking, zero crossing detection, and output timers. Use the ambient temperature

### Loss of Dielectric Protection

The SEL-352 loss of dielectric protection logic uses dc input from pressure switches. Breakers equipped with dielectric gas pressure switches close contacts when the pressure drops below a preset level. One input that indicates current transformer dielectric failure can be used for alarming or tripping. Two additional inputs that monitor two thresholds of the dielectric gas pressure of the interrupter can be used for alarming, tripping, or breaker failure tripping.

compensation available in the SEL-352-2 and SEL-352-3 and dc control voltage compensation in the SEL-352-3 to provide consistent point-on-wave closing results over a wide range of operating conditions.

### Synchronism Checking

Angle and frequency differences between the X-side and the Y-side voltage are compared against two sets of settings. For example, one set of settings may be used to supervise automatic reclosing you programmed in SELOGIC control equations, and the other set of settings may be used to supervise manual closing through an output contact.

### **Zero-Crossing Detection**

The SEL-352 determines when a zero crossing of the measured voltage will occur. The point-on-wave close logic closes the breaker based on this detection and the close output timers.

### **Trapped Charge Detection**

When the SEL-352 detects a positive or negative charge on the line after the breaker opens, the point-on-wave close logic will close on a positive or negative voltage condition, respectively. This minimizes the voltage difference as the breaker closes, minimizing breaker wear.

### Controlled Close Output Timers

The output timer logic allows you to set the SEL-352 according to actual breaker operate times. Point-on-wave closing has better than 200  $\mu$ s accuracy for all three phases.

### Point-on-Wave Opening

Controlled opening of the breaker is useful in helping to reduce re-ignition across the breaker contacts in specific applications. Re-ignition takes place when the arcing time is too short and the contact separation is small. This presents a low dielectric boundary to the recovery voltage after the arc is extinguished, and re-ignition occurs across the open contacts of the breaker. Reignition is especially prevalent in applications, such as shunt-connected reactive loads, where there is a high transient recovery voltage and low load current present at the time the breaker contacts open. The SEL-352-2 and SEL-352-3 relays are capable of providing point-onwave opening control logic. This logic allows the synchronization of maximum breaker contact separation to occur at the voltage peak or zero crossing point, with additional high-resolution timers and voltage and temperature compensation (SEL-352-3) to provide highly repeatable results over a wide range of operating conditions.





Figure 3 Temperature and Voltage Compensation

Table 1 SEL-352 Relay Optional Interface Board Configurations

### Retripping

Retrip your breaker instantaneously or with a time delay. The two available schemes can also be modified to conform to your specifications for qualifying a retrip condition.

### 86BF Trip and Reset

Lockout relay trip and reset logic is provided for installations with and without automatic breaker isolation schemes.

Use Scheme 1 for breaker failure tripping and "Safe to Reset Lockout Relay" conditions.

Use Scheme 2 to automatically isolate the failed breaker with motor-operated disconnects (MOD). The SEL-352 trips the MOD when current drops below a settable threshold. This scheme can also be used to indicate "Safe to Disconnect" conditions for manual disconnect switches.

### Inputs/Outputs

The SEL-352 has many configurations of input and output options. The basic relay has a main board that includes inputs and outputs, but you may add up to two interface boards for expanded input and output capability.

### Main Board

The main board includes seven programmable output contacts, one ALARM contact, and six optoisolated inputs. A jumper allows Output 7 to follow the ALARM.

### Interface Boards

*Table 1* lists the interface boards that expand the dc input and output capability of your SEL-352 to meet your specific needs. Contact the SEL Customer Service Department for ordering options.

|            | Outputs     |   |        | Inputs   |
|------------|-------------|---|--------|----------|
| Board Type | Number Type |   | Number | Туре     |
| 1          | 16          | Standard, Shared Terminals              | 8      | Standard |
| 2          | 12          | Standard, Independent Terminals         | 8      | Standard |
| 4          | 4           | Standard, Independent Terminals         | 16     | Standard |
| 6          | 8           | Fast Hybrid (High Current Interrupting) | 8      | Standard |
| 5          | 12          | Hybrid (High Current Interrupting)      | 8      | Standard |

# Data Recording

### **Event Report**

The SEL-352 saves an event report in nonvolatile memory when any of the following occur:

- ➤ The relay trips
- ► User-selected relay elements, input, or outputs assert
- ► User executes the **TRIGGER** command

Event reporting has three user-selectable configurations:

| Event Length | # of Events Stored |
|--------------|--------------------|
| 15 Cycles    | 72                 |
| 30 Cycles    | 36                 |
| 60 Cycles    | 18                 |

The header of each event gives the date and time stamps of the trigger condition and relay identification. Each event report contains all unfiltered analog measurements, all digital inputs and outputs, and selected digital relay logic elements. The event type, system frequency, and voltage nulling calculations are reported just before the settings. The settings are listed at the end of the report for verification.

The relay stores 64 samples per cycle of unfiltered data. Display options allow the user to view the event in a 4-, 8-, or 64-sample per cycle format and to select the number of event report cycles to display.

### **Sequential Events Recorder**

The SEL-352 stores 512 changes of state for userselected relay elements, inputs, and output contacts. Each record is time tagged to within two milliseconds. The **SER** command allows the user to display a specific range of events based on the date and time stamp.

### Metering

The meter function shows the values of ac current through the breaker, voltage across and on both sides of the breaker, and three-phase real and reactive power of the system at the breaker.

### **Breaker Operation Records**

The SEL-352 stores 512 breaker operation records in nonvolatile memory. The event records contain breaker operation data: event date and time, operation type, electrical and mechanical operating times, interrupted energy, and interrupted current. This information is reported on a per-pole basis.

### **Breaker Operation Summary**

A breaker operation summary report uses data from the breaker operation records to provide breaker information: average and last electrical operating times, average and last mechanical operating times, total interrupted energy, and total interrupted current. The SEL-352-2 and SEL-352-3 add a percent wear estimation to the summary. Use this information to monitor breaker wear and more effectively schedule routine maintenance.

### **Breaker Alarms**

The BALRM (Breaker Alarm) setting is available for indicating specific breaker alarm conditions. Depending on its setting, the BALRM bit indicates dangerous or abnormal conditions related to operation of the circuit breaker.

Breaker alarm occurrences are stored in memory; the memory resets when settings are changed or a loss of power condition occurs. You can set a programmable output contact to close and indicate when the relay detects a breaker alarm condition.

The default relay settings for BALARM set the BALRM bit for one second and store a message in the alarm message buffer when any of the following conditions are detected:

| Failed CB trip resistors put in service  | Potential transformers disagree |
|--|---------------------------------|
| Failed CB close resistors put in service | Current after MOD trip          |
| 52A contradicts voltage                  | MOD contradicts current         |
| Current while open                       | Volts across closed CB          |
| Trip while open                          | Slow trip                       |
| CD did not close                         | Slow close                      |

A history of the breaker alarms is available with the **BREAKER** command.

### Oscillography

Optional software is available to display the SEL-352 event reports in an oscillographic format. Contact the Customer Service Department for more information about the ACSELERATOR Analytic Assistant<sup>®</sup> SEL-5601 Software.

### **Serial Interface**

The SEL-352 is equipped with three EIA-232 serial ports and one isolated EIA-485 serial port. Each serial port operates independently of the other serial ports.

For connecting devices at over 100 feet, fiber-optic transceivers are available. The SEL-2800 and SEL-2810 provide fiber-optic links between devices for electrical isolation and long distance signal transmission. Contact the SEL Customer Service Department for further information.

### Direct SEL-2600A RTD Module Communications

Program any serial port on the SEL-352-2 or SEL-352-3 to accept fiber-based communications from the

SEL-2600A RTD Module. Use an SEL-2600A with the SEL-2800 fiber-optic transceiver on the selected port to provide up to 12 temperature inputs to the relay. Use these temperature inputs for ambient temperature compensation for point-on-wave open and close operations, and as many as 24 individual thermal elements.



Figure 4 Communications with the SEL-2600A RTD Module (SEL-2800 not shown)

### Front Panel

The SEL-352 front panel includes a 2-line, 16-character LCD display; 16 LED target/indicators; and 8 pushbuttons. The LCD display shows event information, metering information, and self-test status. The display is controlled with 8 multifunction pushbuttons.

### Targeting

The target LEDs on the front panel illuminate based on various relay conditions. View these targets remotely by issuing the **TARGET** command to one of the serial ports. Front-panel targets illuminate for the conditions shown in *Table 2*.

Table 2 Front-Panel Target LED Indication

| Target<br>LED | Condition for<br>Illumination | Target<br>LED | Condition for<br>Illumination   |
|---------------|-------------------------------|---------------|---------------------------------|
| Top Row       | :                             | Bottom R      | ow:                             |
| EN            | Normal Operation              | А             | Phase A Breaker<br>Failure      |
| PF            | Breaker Pending<br>Failure    | В             | Phase B Breaker<br>Failure      |
| 86BFT         | Lockout Relay Trip            | С             | Phase C Breaker<br>Failure      |
| 86RS          | Lockout Relay<br>Reset        | FAULT         | Fault Current Protec-<br>tion   |
| TRIP          | Breaker Trip<br>Received      | LOAD          | Load Current Protec-<br>tion    |
| CLOSE         | Breaker Close<br>Received     | UBAL          | Current Unbalance<br>Protection |
| 52A           | 52A Status Input<br>Assertion | FLASH         | Flashover Protection            |
| MOD           | MOD Status Input<br>Assertion | THERM         | Thermal Failure<br>Protection   |

# Time Clock Synchronization (IRIG-B)

The SEL-352 accepts a demodulated IRIG-B format signal for synchronizing its internal clock to some external source such as the SEL-2030 or SEL-2020 Communications Processor or SEL-IDM.

# **Model Variations**

### SEL-352-1 Relay

The SEL-352-1 has provided sophisticated and reliable service for many years. It continues to satisfy the needs of most of our customers. However, we recommend using the SEL-352-2 and SEL-352-3 for new designs because of the additional features they provide.

### SEL-352-2 Relay

The SEL-352-2 provides the following additional features:

- Overcurrent elements for detecting rms overcurrent conditions on a per-pole or three-phase basis (50R, 50RA, 50RB, and 50RC).
- Percent wear function for estimating the amount of breaker contact wear per pole.
- ► BREAKER W command for preloading the number of operations, total current, total energy, and percent wear fields in the operation summary on a per-pole basis.
- ► Direct SEL-2600A RTD module communications
- Ambient temperature compensation for point-onwave breaker opening and closing operations.

### SEL-352-3 Relay

The SEL-352-3 provides the following features in addition to those shown for the SEL-352-2 Relay:

- Battery Voltage Monitoring—up to four setpoints for monitoring station dc battery system health.
- DC Voltage compensation for point-on-wave breaker opening and closing operations.

### **Conventional Terminal Blocks**

This model includes hardware that supports three current inputs, six voltage inputs, six optoisolated inputs, seven programmable output contacts, one alarm contact, three EIA-232 ports, one EIA-485 port, and IRIG-B time code. It uses terminal blocks that support #6 ring terminals. This robust package meets or exceeds numerous industry standard type tests.

This relay is available in a 3.50" (2U), 5.25" (3U), or 7.00" (4U) rack-mount package or 4.9", 6.65", or 8.40" panel-mount package. Additional optoisolated inputs and programmable output contacts are available with the larger packages.

### Plug-In Connectors (Connectorized<sup>®</sup>)

This model includes hardware that supports all of the features of the conventional terminal blocks model. It differs in its use of plug-in connectors instead of terminal blocks. In addition, it provides:

- Quick connect/release hardware for rear-panel terminals
- ► Level-sensitive optoisolated inputs

This robust package meets or exceeds numerous industry standard type tests. It is available in a 5.25" (3U) rack-mount package or a 4.9" panel-mount package.

### AC Diagram

Connect the SEL-352 to the breaker current transformers for current-only, breaker-failure detection. Obtain voltage monitoring with the addition of three voltages on one side of the breaker. Supply at least one voltage on each side of the breaker to obtain synchronism checking. By connecting current and supplying three voltages on each side of the breaker, you can obtain thermal protection in addition to breaker-failure detection, voltage monitoring, and synchronism checking.



Figure 5 Typical External AC Connections

### **DC Diagram**

The following diagrams give a simple example of how the SEL-352 can be connected. Inputs and outputs of the SEL-352 are fully programmable for application flexibility. Optional interface boards provide additional outputs and inputs, as described in *Table 1*.



Figure 6 Example DC Output Contact Connections



Figure 7 Example DC Input Connections

# Front- and Rear-Panel Diagrams





#### Figure 8 SEL-352 Front-Panel Diagrams



i3161c

i3154b



13

Figure 9 SEL-352 Rear-Panel Diagrams

# **Relay Dimensions**

#### RACK-MOUNT CHASSIS

#### PANEL-MOUNT CHASSIS



\* ADD 0.65 (16.5) FOR CONNECTORIZED RELAYS

Figure 10 SEL-352 Dimensions for Rack- and Panel-Mount Models

i9010c

# **Specifications**

#### Compliance

| Designed and manufactured under an ISO 9001 certified quality  |
|--|
| management system  |
| UL Listed to U.S. and Canadian safety standards (File E212775; |
| NRGU, NRGU7)   |
| CE Mark  |
| RCM Mark   |

#### General

#### **Terminal Connections**

**Note:** Terminals or stranded copper wire. Ring terminals are recommended. Minimum temperature rating of 105°C.

| Tightening | Torque, | Terminal | Block |  |
|------------|---------|----------|-------|--|
|            |         |          |       |  |

| Minimum:                    | 9 in-lb (1.1 Nm)  |
|-----------------------------|---|
| Maximum:                    | 12 in-lb (1.3 Nm)   |
| Tightening Torque, Connecto | prized  |
| Minimum:                    | 5 in-lb (0.6 Nm)  |
| Maximum:                    | 7 in-lb (0.8 Nm)  |
| AC Current Inputs           |   |
| 5 A Nominal:                | 15 A continuous, 500 A for 1 s, linear to<br>100 A symmetrical<br>1250 A for 1 cycle                        |
| Burden Rating               | 0.27 VA at 5 A, 2.51 VA at 15 A   |
| 1 A Nominal:                | <ul><li>3 A continuous, 100 A for 1 s, linear to<br/>20 A symmetrical,</li><li>250 A for 1 cycle.</li></ul> |
| Burden Rating               | 0.13 VA at 1 A, 1.31 VA at 3 A  |

#### AC Voltage Inputs

120  $V_{L-N}$ , three-phase, four-wire connection 150 V<sub>L-N</sub> continuous (connect any voltage up to 150 Vac) 365 Vac for 10 s 0.13 VA @ 67 V; 0.45 VA @ 120 V

#### Burden:

#### **Power Supply**

| 24/48 Vdc                       |                                    |
|---------------------------------|------------------------------------|
| Rated Voltage:                  | 24-48 Vdc                          |
| Operational Voltage Range:      | 20-60 Vdc polarity dependent       |
| Vdc Input Ripple:               | 5%                                 |
| Interruption:                   | 30 ms at 48 Vdc                    |
| Burden:                         | <25 W                              |
| 125/250 Vdc or Vac              |                                    |
| Rated Voltage:                  | 125–250 Vdc or Vac                 |
| Operational Voltage Range:      | 85-350 Vdc or 85-264 Vac           |
| Vdc Input Ripple:               | 100%                               |
| Interruption:                   | 30 ms at 125 Vdc                   |
| Burden:                         | <25 W                              |
| Note: Interruption and Ripple p | per IEC 60255-11 [IEC 255-11]:1979 |

### **Output Contacts**

### Standard

| lanuaru     |                                       | dissipation             |    |
|-------------|---------------------------------------|-------------------------|----|
| Make:       | 30 A per IEEE C37.90:1989             | 24 V                    | 1  |
|             | I I I I I I I I I I I I I I I I I I I | 48 V                    | 1  |
| Carry:      | 6 A continuous carry at 70°C          | 125 V                   | 1  |
|             | 4 A continuous carry at 85°C          | 250 V                   | 1  |
| 1 s Rating: | 50 A                                  | Note: Fast High Current | Iı |
|             |                                       |                         |    |

| MOV Protection:  | 2'   | 70 Vac, 360 Vdc, 40 J  |
|--|--|--|
| Pickup Time:   | <  | 5 ms   |
| Dropout Time:  | <  | 5 ms, typical  |
| Breaking Capacity (10  | ,000 Oper  | ations) per IEC 60255-23:1994  |
| 24 V   | 0.75 A   | L/R = 40  ms   |
| 48 V<br>125 V  | 0.50 A   | L/R = 40  ms<br>L/R = 40  ms   |
| 250 V  | 0.20 A   | L/R = 40  ms   |
| Cyclic Capacity (10,00<br>Rate: 2.5 cycles/seco  | 0 Operati<br>ond   | ons) per IEC 60255-23:1994   |
| 24 V   | 0.75 A   | L/R = 40  ms   |
| 48 V   | 0.50 A   | L/R = 40  ms   |
| 125 V<br>250 V   | 0.30 A<br>0.20 A   | L/R = 40  ms<br>L/R = 40  ms   |
| High Current Interrup  | ting Optio   | on   |
| Make:  | 3(   | ) A per IEEE C37.90:1989   |
| Carry:   | 6  | A continuous carry at 70°C   |
| 1 c Pating:  | 51   |  |
| 1 S Raung.   | 2  | 20 V-L 120 L   |
| MOV Protection:  | 3.   | 30 Vdc, 130 J  |
| Pickup Time:   | <  | 5 ms   |
| Dropout Time:  | <  | 8 ms, typical  |
| Breaking Capacity (10  | ,000 Oper  | rations) per IEC 60255-23:1994   |
| 24 V   | 10.0 A   | L/R = 40  ms   |
| 48 V<br>125 V  | 10.0 A   | L/R = 40  ms<br>L/R = 40  ms   |
| 250 V  | 10.0 A   | L/R = 20  ms   |
|  |  |  |
| Cyclic Capacity (10,00<br>Rate: 4 cycles in 1 se<br>dissipation  | 0 Operati<br>econd, foll   | ons) per IEC 60255-23:1994<br>lowed by 2 minutes idle for thermal  |
| Cyclic Capacity (10,00<br>Rate: 4 cycles in 1 se<br>dissipation<br>24 V  | 00 Operati<br>econd, foll<br>10.0 A  | ons) per IEC 60255-23:1994<br>lowed by 2 minutes idle for thermal<br>L/R = 40 ms   |
| Cyclic Capacity (10,00<br>Rate: 4 cycles in 1 se<br>dissipation<br>24 V<br>48 V<br>125 V   | 00 Operati<br>econd, foll<br>10.0 A<br>10.0 A  | ons) per IEC 60255-23:1994<br>lowed by 2 minutes idle for thermal<br>L/R = 40  ms<br>L/R = 40  ms  |
| Cyclic Capacity (10,00<br>Rate: 4 cycles in 1 so<br>dissipation<br>24 V<br>48 V<br>125 V<br>250 V  | 00 Operati<br>2000 A<br>10.0 A<br>10.0 A<br>10.0 A<br>10.0 A   | ons) per IEC 60255-23:1994<br>lowed by 2 minutes idle for thermal<br>L/R = 40 ms<br>L/R = 40 ms<br>L/R = 40 ms<br>L/R = 20 ms  |
| Cyclic Capacity (10,00<br>Rate: 4 cycles in 1 se<br>dissipation<br>24 V<br>48 V<br>125 V<br>250 V<br>Note: Do not use high-c<br>control signals. These   | 00 Operati<br>econd, foll<br>10.0 A<br>10.0 A<br>10.0 A<br>10.0 A<br>urrent inte<br>outputs are  | ons) per IEC 60255-23:1994<br>lowed by 2 minutes idle for thermal<br>L/R = 40 ms<br>L/R = 40 ms<br>L/R = 40 ms<br>L/R = 20 ms<br>rrupting output contacts to switch ac<br>e polarity-dependent.  |
| Cyclic Capacity (10,00<br>Rate: 4 cycles in 1 so<br>dissipation<br>24 V<br>48 V<br>125 V<br>250 V<br>Note: Do not use high-c<br>control signals. These<br>Fast High Current Inte   | 00 Operati<br>econd, foll<br>10.0 A<br>10.0 A<br>10.0 A<br>10.0 A<br>urrent inte<br>outputs are<br>rrupting  | ons) per IEC 60255-23:1994<br>lowed by 2 minutes idle for thermal<br>L/R = 40  ms<br>L/R = 40  ms<br>L/R = 40  ms<br>L/R = 20  ms<br>rrupting output contacts to switch ac<br>polarity-dependent.<br>Option  |
| Cyclic Capacity (10,00<br>Rate: 4 cycles in 1 se<br>dissipation<br>24 V<br>48 V<br>125 V<br>250 V<br>Note: Do not use high-c<br>control signals. These<br>Fast High Current Inte<br>Make:  | 00 Operati<br>econd, foll<br>10.0 A<br>10.0 A<br>10.0 A<br>10.0 A<br>urrent inte<br>outputs are<br>rrupting<br>30  | ons) per IEC 60255-23:1994<br>lowed by 2 minutes idle for thermal<br>L/R = 40  ms<br>L/R = 40  ms<br>L/R = 40  ms<br>L/R = 20  ms<br>rrupting output contacts to switch ac<br>e polarity-dependent.<br>Option<br>0 A per IEEE C37.90:1989  |
| Cyclic Capacity (10,00<br>Rate: 4 cycles in 1 se<br>dissipation<br>24 V<br>48 V<br>125 V<br>250 V<br>Note: Do not use high-c<br>control signals. These<br>Fast High Current Inte<br>Make:<br>Carry:  | 00 Operati<br>econd, foll<br>10.0 A<br>10.0 A<br>10.0 A<br>10.0 A<br>urrent inte<br>outputs are<br>rrupting<br>30<br>6<br>4  | ons) per IEC 60255-23:1994<br>lowed by 2 minutes idle for thermal<br>L/R = 40  ms<br>L/R = 40  ms<br>L/R = 20  ms<br>rrupting output contacts to switch ac<br>e polarity-dependent.<br>Option<br>0 A per IEEE C37.90:1989<br>A continuous carry at 70°C<br>A continuous carry at 85°C  |
| Cyclic Capacity (10,00<br>Rate: 4 cycles in 1 se<br>dissipation<br>24 V<br>48 V<br>125 V<br>250 V<br>Note: Do not use high-c<br>control signals. These<br>Fast High Current Inte<br>Make:<br>Carry:<br>1 s Rating:   | 00 Operati<br>econd, foll<br>10.0 A<br>10.0 A<br>10.0 A<br>10.0 A<br>urrent inte<br>outputs arc<br>rrupting<br>30<br>6<br>4  | ons) per IEC 60255-23:1994<br>lowed by 2 minutes idle for thermal<br>L/R = 40 ms<br>L/R = 40 ms<br>L/R = 20 ms<br>rrupting output contacts to switch ac<br>e polarity-dependent.<br>Option<br>0 A per IEEE C37.90:1989<br>A continuous carry at 70°C<br>A continuous carry at 85°C   |
| Cyclic Capacity (10,00<br>Rate: 4 cycles in 1 sc<br>dissipation<br>24 V<br>48 V<br>125 V<br>250 V<br>Note: Do not use high-c<br>control signals. These<br>Fast High Current Inte<br>Make:<br>Carry:<br>1 s Rating:<br>MOV Protection:  | 00 Operati<br>200 Operati<br>200 A<br>10.0 A<br>10.0 A<br>10.0 A<br>10.0 A<br>200 | ons) per IEC 60255-23:1994<br>lowed by 2 minutes idle for thermal<br>L/R = 40 ms<br>L/R = 40 ms<br>L/R = 20 ms<br>rrupting output contacts to switch ac<br>e polarity-dependent.<br>Option<br>0 A per IEEE C37.90:1989<br>A continuous carry at 70°C<br>A continuous carry at 85°C<br>0 A<br>30 Vdc. 40 J  |
| Cyclic Capacity (10,00<br>Rate: 4 cycles in 1 se<br>dissipation<br>24 V<br>48 V<br>125 V<br>250 V<br>Note: Do not use high-c<br>control signals. These<br>Fast High Current Inte<br>Make:<br>Carry:<br>1 s Rating:<br>MOV Protection:<br>Pickun Time:  | 00 Operati<br>200 Operati<br>200 A<br>10.0 A<br>10.0 A<br>10.0 A<br>200  | ons) per IEC 60255-23:1994<br>lowed by 2 minutes idle for thermal<br>L/R = 40 ms<br>L/R = 40 ms<br>L/R = 20 ms<br>rrupting output contacts to switch ac<br>polarity-dependent.<br>Option<br>0 A per IEEE C37.90:1989<br>A continuous carry at 70°C<br>A continuous carry at 85°C<br>0 A<br>30 Vdc, 40 J<br>200 ms  |
| Cyclic Capacity (10,00<br>Rate: 4 cycles in 1 se<br>dissipation<br>24 V<br>48 V<br>125 V<br>250 V<br>Note: Do not use high-c<br>control signals. These<br>Fast High Current Inte<br>Make:<br>Carry:<br>1 s Rating:<br>MOV Protection:<br>Pickup Time:<br>Dropout Time:   | 00 Operati<br>econd, foll<br>10.0 A<br>10.0 A<br>10.0 A<br>10.0 A<br>urrent inte<br>outputs arc<br>rrupting<br>30<br>6<br>4<br>50<br>33  | ons) per IEC 60255-23:1994<br>lowed by 2 minutes idle for thermal<br>L/R = 40  ms<br>L/R = 40  ms<br>L/R = 20  ms<br>rrupting output contacts to switch ac<br>e polarity-dependent.<br>Option<br>0 A per IEEE C37.90:1989<br>A continuous carry at 70°C<br>A continuous carry at 85°C<br>0 A<br>30 Vdc, 40 J<br>200 ms<br>8 us typical   |
| Cyclic Capacity (10,00<br>Rate: 4 cycles in 1 so<br>dissipation<br>24 V<br>48 V<br>125 V<br>250 V<br>Note: Do not use high-c<br>control signals. These<br>Fast High Current Inte<br>Make:<br>Carry:<br>1 s Rating:<br>MOV Protection:<br>Pickup Time:<br>Dropout Time:   | 00 Operati<br>econd, foll<br>10.0 A<br>10.0 A<br>10.0 A<br>10.0 A<br>urrent inte<br>outputs are<br>rrupting<br>30<br>6<br>4<br>50<br>31<br>50<br>32<br>4<br>50<br>32<br>4<br>50<br>32<br>4<br>50<br>32<br>4<br>50<br>32<br>32<br>4<br>50<br>32<br>32<br>50<br>32<br>50<br>32<br>50<br>32<br>50<br>32<br>50<br>50<br>50<br>50<br>50<br>50<br>50<br>50<br>50<br>50<br>50<br>50<br>50   | ons) per IEC 60255-23:1994<br>lowed by 2 minutes idle for thermal<br>L/R = 40  ms<br>L/R = 40  ms<br>L/R = 40  ms<br>L/R = 20  ms<br>rrupting output contacts to switch ac<br>e polarity-dependent.<br>Option<br>0 A per IEEE C37.90:1989<br>A continuous carry at 70°C<br>A continuous carry at 85°C<br>0 A<br>30 Vdc, 40 J<br>200 ms<br>8 µs, typical  |
| Cyclic Capacity (10,00<br>Rate: 4 cycles in 1 so<br>dissipation<br>24 V<br>48 V<br>125 V<br>250 V<br>Note: Do not use high-c<br>control signals. These<br>Fast High Current Inte<br>Make:<br>Carry:<br>1 s Rating:<br>MOV Protection:<br>Pickup Time:<br>Dropout Time:<br>Breaking Capacity (10  | 00 Operati<br>200 A<br>10.0 A<br>10.0 A<br>10.0 A<br>10.0 A<br>10.0 A<br>10.0 A<br>10.0 A<br>200 A<br>200 A<br>200 Oper<br>200 Oper  | ons) per IEC 60255-23:1994<br>lowed by 2 minutes idle for thermal<br>L/R = 40 ms<br>L/R = 40 ms<br>L/R = 20 ms<br>rrupting output contacts to switch ac<br>e polarity-dependent.<br>Option<br>0 A per IEEE C37.90:1989<br>A continuous carry at 70°C<br>A continuous carry at 85°C<br>0 A<br>30 Vdc, 40 J<br>200 ms<br>8 µs, typical<br>ations) per IEC 60255-23:1994  |
| Cyclic Capacity (10,00<br>Rate: 4 cycles in 1 sc<br>dissipation<br>24 V<br>48 V<br>125 V<br>250 V<br>Note: Do not use high-c<br>control signals. These<br>Fast High Current Inte<br>Make:<br>Carry:<br>1 s Rating:<br>MOV Protection:<br>Pickup Time:<br>Dropout Time:<br>Breaking Capacity (10<br>24 V<br>48 V  | 00 Operati<br>200 Operati<br>200 A<br>10.0 A<br>10.0 A<br>10.0 A<br>10.0 A<br>200 A<br>200 Oper<br>10.0 A<br>10.0 A  | ons) per IEC 60255-23:1994<br>lowed by 2 minutes idle for thermal<br>L/R = 40 ms<br>L/R = 40 ms<br>L/R = 20 ms<br>rrupting output contacts to switch ac<br>e polarity-dependent.<br>Option<br>D A per IEEE C37.90:1989<br>A continuous carry at 70°C<br>A continuous carry at 85°C<br>D A<br>30 Vdc, 40 J<br>200 ms<br>8 µs, typical<br>rations) per IEC 60255-23:1994<br>L/R = 40 ms<br>L/R = 40 ms   |
| Cyclic Capacity (10,00<br>Rate: 4 cycles in 1 se<br>dissipation<br>24 V<br>48 V<br>125 V<br>250 V<br>Note: Do not use high-c<br>control signals. These<br>Fast High Current Inte<br>Make:<br>Carry:<br>1 s Rating:<br>MOV Protection:<br>Pickup Time:<br>Dropout Time:<br>Breaking Capacity (10<br>24 V<br>48 V<br>125 V   | 00 Operati<br>econd, foll<br>10.0 A<br>10.0 A<br>10.0 A<br>10.0 A<br>urrent inte<br>outputs are<br>rrupting<br>30<br>6<br>4<br>50<br>33<br><<br><<br>,000 Oper<br>10.0 A<br>10.0 A<br>10.0 A   | ons) per IEC 60255-23:1994<br>lowed by 2 minutes idle for thermal<br>L/R = 40 ms<br>L/R = 40 ms<br>L/R = 20 ms<br>rrupting output contacts to switch ac<br>polarity-dependent.<br>Option<br>0 A per IEEE C37.90:1989<br>A continuous carry at 70°C<br>A continuous carry at 85°C<br>0 A<br>30 Vdc, 40 J<br>200 ms<br>8 µs, typical<br>rations) per IEC 60255-23:1994<br>L/R = 40 ms<br>L/R = 40 ms<br>L/R = 40 ms<br>L/R = 40 ms   |
| Cyclic Capacity (10,00<br>Rate: 4 cycles in 1 sc<br>dissipation<br>24 V<br>48 V<br>125 V<br>250 V<br>Note: Do not use high-c<br>control signals. These<br>Fast High Current Inte<br>Make:<br>Carry:<br>1 s Rating:<br>MOV Protection:<br>Pickup Time:<br>Dropout Time:<br>Breaking Capacity (10<br>24 V<br>48 V<br>125 V<br>250 V  | 00 Operati<br>econd, foll<br>10.0 A<br>10.0 A<br>10.0 A<br>10.0 A<br>urrent inte<br>outputs arc<br>rrupting<br>30<br>6<br>4<br>50<br>33<br><<br><<br><<br>000 Oper<br>10.0 A<br>10.0 A<br>10.0 A<br>10.0 A<br>10.0 A   | ons) per IEC 60255-23:1994<br>lowed by 2 minutes idle for thermal<br>L/R = 40 ms<br>L/R = 40 ms<br>L/R = 20 ms<br>rrupting output contacts to switch ac<br>e polarity-dependent.<br>Option<br>0 A per IEEE C37.90:1989<br>A continuous carry at 70°C<br>A continuous carry at 85°C<br>0 A<br>30 Vdc, 40 J<br>200 ms<br>8 µs, typical<br>rations) per IEC 60255-23:1994<br>L/R = 40 ms<br>L/R = 20 ms  |
| Cyclic Capacity (10,00<br>Rate: 4 cycles in 1 sc<br>dissipation<br>24 V<br>48 V<br>125 V<br>250 V<br>Note: Do not use high-c<br>control signals. These<br>Fast High Current Inte<br>Make:<br>Carry:<br>1 s Rating:<br>MOV Protection:<br>Pickup Time:<br>Dropout Time:<br>Breaking Capacity (10<br>24 V<br>48 V<br>125 V<br>250 V<br>Cyclic Capacity (10,00<br>Rate: 4 cycles in 1 sc<br>dissipation   | 00 Operati<br>econd, foll<br>10.0 A<br>10.0 A<br>10.0 A<br>10.0 A<br>urrent inte<br>outputs arc<br>rrupting<br>30<br>6<br>4<br>50<br>33<br><<br><<br><<br>000 Oper<br>10.0 A<br>10.0 A<br>10.0 A<br>10.0 A<br>0.0 Operati<br>econd, foll   | ons) per IEC 60255-23:1994<br>lowed by 2 minutes idle for thermal<br>L/R = 40  ms<br>L/R = 40  ms<br>L/R = 20  ms<br>rrupting output contacts to switch ac<br>e polarity-dependent.<br>Option<br>0 A per IEEE C37.90:1989<br>A continuous carry at 70°C<br>A continuous carry at 85°C<br>0 A<br>30 Vdc, 40 J<br>200 ms<br>8 µs, typical<br>ations) per IEC 60255-23:1994<br>L/R = 40  ms<br>L/R = 40  ms<br>L/R = 40  ms<br>L/R = 20  ms<br>ons) per IEC 60255-23:1994<br>lowed by 2 minutes idle for thermal  |
| Cyclic Capacity (10,00<br>Rate: 4 cycles in 1 sc<br>dissipation<br>24 V<br>48 V<br>125 V<br>250 V<br>Note: Do not use high-c<br>control signals. These<br>Fast High Current Inte<br>Make:<br>Carry:<br>1 s Rating:<br>MOV Protection:<br>Pickup Time:<br>Dropout Time:<br>Breaking Capacity (10<br>24 V<br>48 V<br>125 V<br>250 V<br>Cyclic Capacity (10,00<br>Rate: 4 cycles in 1 sc<br>dissipation<br>24 V                                   | 00 Operati<br>econd, foll<br>10.0 A<br>10.0 A<br>10.0 A<br>10.0 A<br>urrent inte<br>outputs arc<br>rrupting<br>30<br>6<br>4<br>50<br>32<br><<br>000 Operati<br>2000 A<br>10.0 A<br>10.0 A<br>10.0 A<br>10.0 A  | ons) per IEC 60255-23:1994<br>lowed by 2 minutes idle for thermal<br>L/R = 40  ms<br>L/R = 40  ms<br>L/R = 20  ms<br>rrupting output contacts to switch ac<br>e polarity-dependent.<br>Option<br>0 A per IEEE C37.90:1989<br>A continuous carry at 70°C<br>A continuous carry at 85°C<br>0 A<br>30 Vdc, 40 J<br>200 ms<br>8 µs, typical<br>rations) per IEC 60255-23:1994<br>L/R = 40  ms<br>L/R = 40  ms<br>L/R = 20  ms<br>ons) per IEC 60255-23:1994<br>lowed by 2 minutes idle for thermal<br>L/R = 40  ms   |
| Cyclic Capacity (10,00<br>Rate: 4 cycles in 1 sc<br>dissipation<br>24 V<br>48 V<br>125 V<br>250 V<br>Note: Do not use high-c<br>control signals. These<br>Fast High Current Inte<br>Make:<br>Carry:<br>1 s Rating:<br>MOV Protection:<br>Pickup Time:<br>Dropout Time:<br>Dropout Time:<br>Breaking Capacity (10<br>24 V<br>48 V<br>125 V<br>250 V<br>Cyclic Capacity (10,00<br>Rate: 4 cycles in 1 sc<br>dissipation<br>24 V<br>48 V<br>125 V | 00 Operati<br>econd, foll<br>10.0 A<br>10.0 A<br>10.0 A<br>10.0 A<br>urrent inte<br>outputs are<br>rrupting<br>30<br>6<br>4<br>50<br>33<br><<br><<br><<br>,000 Oper<br>10.0 A<br>10.0 A<br>10.0 A<br>10.0 A<br>10.0 A<br>10.0 A<br>10.0 A<br>10.0 A  | ons) per IEC 60255-23:1994<br>lowed by 2 minutes idle for thermal<br>L/R = 40  ms<br>L/R = 40  ms<br>L/R = 20  ms<br>rrupting output contacts to switch ac<br>e polarity-dependent.<br>Option<br>0 A per IEEE C37.90:1989<br>A continuous carry at 70°C<br>A continuous carry at 85°C<br>0 A<br>30 Vdc, 40 J<br>200 ms<br>8 µs, typical<br>rations) per IEC 60255-23:1994<br>L/R = 40  ms<br>L/R = 40  ms<br>L/R = 20  ms<br>ons) per IEC 60255-23:1994<br>lowed by 2 minutes idle for thermal<br>L/R = 40  ms<br>L/R = 40  ms<br>L/R = 40  ms<br>L/R = 40  ms<br>L/R = 40  ms |

nterrupting Option output contacts are not polarity dependent.

|  | 0 | pto | iso | lated | In | puts |
|--|---|-----|-----|-------|----|------|
|--|---|-----|-----|-------|----|------|

| 250 Vdc<br>125 Vdc  | Pickup Dropout   200–300 Vdc 150 Vdc   105–150 Vdc 75 Vdc   |                              |
|---|---|------------------------------|
| 110 Vdc   | 88–132 Vdc 66 Vdc   |                              |
| 48 Vdc:<br>24 Vdc   | 38.4–60 Vdc 28.8 Vdc<br>15.0–30 Vdc   | Conducted Im                 |
| Note: 24, 48, 125 Vdc op<br>current, 110 Vdc inputs<br>inputs draw approximat<br>nominal input voltage. | toisolated inputs draw approximately 4 mA of<br>draw approximately 8 mA of current, and 250 Vdc<br>tely 5 mA of current. All current ratings are at |                              |
| Substation Battery Volt   | age Monitor   | Electrostatic I<br>Immunity: |
| Pickup Range:   | 20–300 Vdc  | 2                            |
| Pickup Accuracy:  | ±2% of setting  | Fast Transien                |
| Routine Dielectric Stre   | ngth  | Immunity:                    |
| AC Current and Voltage<br>Inputs:   | 2500 Vac for 10 s   | S                            |
| Power Supply, Optoisol<br>Inputs, and Output<br>Contacts:   | lated<br>3100 Vdc for 10 s  | Surge Immun                  |
| Frequency and Rotation  | 1   |                              |
| System Frequency:   | 50 or 60 Hz   | Slow Damped                  |
| Phase Rotation:   | ABC or ACB  | Wave:                        |
| Frequency Tracking  |   |                              |
| NFREQ = $60$ :  | Tracking range is 55–63 Hz  |                              |
| NFREQ = 50:   | Tracking range is 45–55 Hz  | IEEE Surge V                 |
| <b>Communications Ports</b>   |   | Capability.                  |
| EIA-232:  | 1 front and 2 rear  |                              |
| EIA-485:  | 1 rear, 2100 Vdc isolation  |                              |
| Baud rate:  | 300-19200 baud  |                              |
| Time-Code Input   |   |                              |
| Relay accepts demodula<br>is time synchronized t  | ated IRIG-B time-code input at Port 1 or 2. Relay to within ±5 ms of time source input.   | Power Supply                 |
| Operating Temperature   |   |                              |
| $-40^{\circ}$ to $+85^{\circ}$ C ( $-40^{\circ}$ to   | +185°F)   |                              |
| Weight  |   |                              |
| 2U Rack Unit Height:  | 15 lbs (6.8 kg)   |                              |
| 3U Rack Unit Height:  | 17.75 lbs (8 kg)  | Fnvironmental                |
| Processing Specificatio   | ns  | Cold:                        |
| 64 samples per power s  | ystem cycle   | colu.                        |
| Type Tests  |   | Den Haste                    |
| Electromagnetic Compa   | atibility Emissions   | Dry Heat:                    |
| Radiated Emissions:   | EN 60255-25:200<br>EN 55011:1998 + A1:1999 + A2:2002<br>CISPR 11:1997 (Mod) + A1:1999 +<br>A2:2002  | Damp Heat, C                 |
|   | Severity Level: Class A   | Vibration:                   |
| Conducted Emissions:  | EN 60255-25:2000<br>Severity Level: Class A   |                              |
| Electromagnetic Compa   | atibility (EMC) Immunity  | Shock & Bun                  |
| Radiated Immunity:  | EN 61000-4-3:2006 + A1:2008   |                              |
|   | 10 V/m <sub>RMS</sub> ;<br>80 MHz – 1 GHz; 1.4 GHz – 2.7 GHz:<br>Swept;<br>80, 160, 380, 450, 900, 1850, & 2150<br>MHz: Spot (> 15 V/m_ = c/20% AM  | Seismic:                     |
|   | 1 kHz sine wave)  |                              |

IEEE C37.90.2-2004 20 V/m<sub>RMS</sub>; 80 MHz - 1 GHz: Swept Frequency 80, 160, 450, 900 MHz: Spot Frequency (> 35 V/m<sub>RMS</sub> w/80% AM 1 kHz sine wave) EN 61000-4-6:2007 Conducted Immunity: 10  $V_{RMS};\,150~kHz-80~MHz;$  Swept Frequency 27 MHz & 68 MHz: Spot Frequency (w/80% AM 1 kHz sine wave) Electrostatic Discharge EN 61000-4-2:2009 IEEE C37.90.3 - 2001 Severity Level: 2, 4, 6, & 8 kV contact; 2, 4, 8, & 15 kV air Fast Transient/Burst EN 61000-4-4:2004 Zone A: Power Input; I/O; ± 4.0 kV; 5 kV Communication Ports: ± 2.0 kV; 5 kV EN60255-22-1:2008 Surge Immunity: Zone B: ± 0.5, 1.0 kV (line-to-line)  $\pm 0.5, 1.0, 2.0$  kV (line-to-earth) ± 0.5, 1.0 kV (communication ports) EN 60255-22-1:2008 Slow Damped Oscillatory Common Mode: Power Input, CT, PT, & I/O: ± 2.5 kV Communication Ports: ± 1.0 kV Differential Mode: Power input; PT & I/O: ± 1.0 kV IEEE Surge Withstand IEEE C37.90.1-2002 Damped Oscillatory (1 MHz): Power Input, CT, PT, & I/O: ± 2.5 kV (CM & DM) Communications Ports: ± kV (CM only) Fast Transient (2.5 kHz): Power Input, CT, PT, & I/O: ± 4.0 kV (CM & DM) Communications Ports: ± 4.0 kV (CM only) EN 60255-11:2010 Power Supply Immunity: Voltage dips, interruption, & ripple EN 61000-4-11:2004 AC dips & interruptions EN 61000-4-29:2000 DC dips & interruptions EN 61000-4-17:1999 + A1:2004 15% ripple on dc power input EN 60068-2-1:2007 Cold profile ad;  $-40^{\circ}C \ge 16$  hrs, operational EN 60068-2-2:2007 Dry heat profile db;  $+85^{\circ}C \ge hrs$ , operational EN 60068-2-30:2005 Damp Heat, Cyclic: Damp heat, profile db, -25°C to +55°C, relative humidity  $\geq 93\%$ , 6 cycles EN 60255-21-1:1995 Class 1 vibration endurance Class 2 vibration response EN 60255-21-3:1995 Shock & Bump: Class 1 shock withstand Class 2 shock response Class 1 bump

EN 60255-21-3:1995 Class 2 quake response Insulation Coordination:

 $\begin{array}{l} \text{EN } 60255\text{-}5:2001 \\ \text{IEEE } C37.90\text{-}2005 \\ \text{Hi-Pot:} \\ 3.1 \ kV_{dc} \ \text{power supply} \\ 2.5 \ kV_{ac} \ \text{contact } I/O \ \& \ analog \ inputs \\ 2.2 \ kV_{dc} \ \text{EIA-485} \ \& \ IRIG \\ \text{Impulse: } 0.5 \ J, \ 5 \ kV, \ 1.2/50 \ uS \end{array}$ 

#### Signal Processing Specifications

#### **Analog Data Acquisition**

-3dB cutoff at 1200 Hz, 64 samples per cycle, see Figure 11.



| Harmonic                | Correction Factor<br>(60 Hz) | Correction Factor<br>(50 Hz) |
|-------------------------|------------------------------|------------------------------|
| Fundamental through 8th |                              |                              |
| 9th                     | 1.01                         | 1                            |
| 10th                    | 1.02                         | 1.01                         |
| 11th                    | 1.03                         | 1.01                         |
| 12th                    | 1.05                         | 1.02                         |
| 13th                    | 1.07                         | 1.03                         |
| 14th                    | 1.10                         | 1.04                         |
| 15th                    | 1.14                         | 1.06                         |
| 16th                    | 1.18                         | 1.08                         |
| 17th                    | 1.23                         | 1.11                         |
| 18th                    | 1.28                         | 1.14                         |
| 19th                    | 1.35                         | 1.17                         |
| 20th                    | 1.42                         | 1.21                         |
| 21st                    | 1.50                         | 1.25                         |
| 22nd                    | 1.59                         | 1.30                         |
| 23rd                    | 1.68                         | 1.36                         |
| 24th                    | 1.78                         | 1.42                         |
| 25th                    | 1.89                         | 1.48                         |
| 26th                    | 2.01                         | 1.56                         |
| 27th                    | 2.14                         | 1.63                         |
| 28th                    | 2.27                         | 1.72                         |
| 29th                    | 2.40                         | 1.80                         |

| Harmonic   | Correction Factor<br>(60 Hz) | Correction Factor<br>(50 Hz) |  |  |
|--|------------------------------|------------------------------|--|--|
| 30th   | 2.55                         | 1.89                         |  |  |
| 31st   | 2.70                         | 1.99                         |  |  |
| 32nd 2.86 2.09   |                              |                              |  |  |
| Relay Measurement • Correction Factor = Input Signal Level |                              |                              |  |  |

#### Figure 11 Analog Filter Curve

#### Digital Filtering

Half-cosine filter for the 50FT overcurrent element Cosine filter for all other elements

Processing Intervals

1/8-Cycle:

| Event Report Triggers             |
|-----------------------------------|
| Targets                           |
| Optoisolated Inputs               |
| Local Bits                        |
| Remote Bits                       |
| SELOGIC Control Equation SET A    |
| Elements                          |
| Fault Current Protection Elements |
| 86BF Trip and Reset Elements      |
| Contact Output Elements           |
| SELOGIC Control Equation Analog   |
| Compares                          |
| All other elements                |
|                                   |

#### **Relay Element Specifications**

#### **Overcurrent Elements**

1/4-Cycle:

50FT Fault Current Element with Subsidence Current Logic

| Setting Ranges:               | 0.50–45.00 A secondary, 0.01-A steps ( $I_{NOM}$ = 5 A)<br>0.10–9.00 A secondary, 0.01-A steps ( $I_{NOM}$ = 1 A) |
|-------------------------------|---|
| Pickup Time:                  | <0.55 cycle at 2 multiples of pickup  |
| Dropout Time:                 | <0.75 cycle   |
| Pickup and Dropout:           | $\pm 0.025$ A secondary $\pm 5\%$ of setting  |
| Transient Overreach:          | ±14% of setting   |
| 50MD/50LD MOD and L           | load/Line Current Elements  |
| Setting Ranges:               | 0.10–45.00 A secondary, 0.01-A steps ( $I_{NOM}$ = 5 A)<br>0.02–9.00 A secondary, 0.01-A steps ( $I_{NOM}$ = 1 A) |
| Pickup Time:                  | < 0.9 cycle at 2 multiples of pickup  |
| Dropout Time:                 | <1.35 cycles  |
| Pickup and Dropout:           | $\pm 0.03$ A secondary $\pm 5\%$ of setting   |
| Transient Overreach:          | ±5% of setting  |
| 50MN Minimum Current          | Element   |
| Current Threshold<br>(Fixed): | 0.10 A secondary ( $I_{NOM} = 5 A$ )<br>0.02 A secondary ( $I_{NOM} = 1 A$ )                                      |
| Pickup Time:                  | <0.9 cycle at 2 multiples of pickup   |
| Dropout Time:                 | <1.35 cycles  |
| Pickup and Dropout:           | ±0.03 A secondary   |
| Transient Overreach:          | ±5% of setting  |
| 50N Ground Overcurrent        | Element   |
| Setting Ranges:               | 0.10–45.00 A secondary, 0.01-A steps ( $I_{NOM}$ = 5 A)<br>0.02–9.00 A secondary, 0.01-A steps ( $I_{NOM}$ = 1 A) |
| Pickup Time:                  | <0.9 cycle at 2 multiples of pickup   |
| Dropout Time:                 | <1.35 cycles  |

| Pickup and Dropout:                                | $\pm 0.025$ A secondary $\pm 5\%$ of setting   |
|--|--|
| Transient Overreach:                               | ±5% of setting   |
| 50RMS RMS Overcurren<br>(Only available in the SEI | t Element<br>L-352-2 and SEL-352-3 Relays)   |
| Setting Ranges:                                    | $\begin{array}{l} 0.50{-}45.00 \text{ A secondary, } 0.10{-}\text{A steps} \\ (I_{\text{NOM}} = 5 \text{ A}) \\ 0.10{-}9.00 \text{ A secondary, } 0.02{-}\text{A steps} \\ (I_{\text{NOM}} = 1 \text{ A}) \end{array}$ |
| Pickup Time:                                       | <0.9 cycle at 2 multiples of pickup  |
| Dropout Time:                                      | <1.125 cycles  |
| Pickup and Dropout:                                | $\pm 0.01$ • $I_{NOM}$ A secondary $\pm$ 5% of setting   |
| Transient Overreach:                               | ±5% of setting   |
|  |  |

#### Pickup/Dropout Curves

*Figure 12* through *Figure 15* are based on actual test data at room temperature using various settings. Relay element specifications given previously in this section include the entire temperature range of the relay. Output contact times are not included.



#### Figure 12 50FT Pickup Curves



Figure 13 50FT Dropout Curves









#### Voltage Elements

| 87H/87FO/87TH Voltage      | Across Breaker Overvoltage Elements               |  |
|----------------------------|---|--|
| Setting Range:             | 1.0-150.0 V secondary, 0.1-V steps                |  |
| Pickup Time:               | <1.35 cycles                                      |  |
| Dropout Time:              | <1.55 cycles                                      |  |
| Pickup and Dropout:        | $\pm 0.09$ V secondary $\pm 5\%$ of setting       |  |
| Transient Overreach:       | ±5% of setting                                    |  |
| X47Q/Y47Q Negative-Se      | quence Overvoltage Element                        |  |
| Setting Range:             | 2.0-140.0 V secondary, 0.1-V steps                |  |
| Pickup Time:               | <1.35 cycles                                      |  |
| Dropout Time:              | <1.55 cycles                                      |  |
| Pickup and Dropout:        | $\pm 0.27$ V secondary $\pm 6\%$ of setting       |  |
| Transient Overreach:       | ±5% of setting                                    |  |
| X59H High-Set Overvolta    | age Element                                       |  |
| Setting Range:             | 1.0-130.0 V secondary, 0.1-V steps                |  |
| Pickup Time:               | <1.35 cycles                                      |  |
| Dropout Time:              | <1.55 cycles                                      |  |
| Pickup and Dropout:        | $\pm 0.09$ V secondary $\pm 5\%$ of setting       |  |
| Transient Overreach:       | ±5% of setting                                    |  |
| X27D/Y27D Dead Line U      | Jndervoltage Element                              |  |
| Setting Range:             | 1.0-120.0 V secondary, 0.1-V steps                |  |
| Pickup Time:               | <1.35 cycles                                      |  |
| Dropout Time:              | <1.55 cycles                                      |  |
| Pickup and Dropout:        | $\pm 0.09$ V secondary $\pm 5\%$ of setting       |  |
| Transient Overreach:       | ±5% of setting                                    |  |
| X59L/Y59L Live Line Ov     | vervoltage Element                                |  |
| Setting Range:             | 10.0-120.0 V secondary, 0.1-V steps               |  |
| Pickup Time:               | <1.35 cycles                                      |  |
| Dropout Time:              | <1.55 cycles                                      |  |
| Pickup and Dropout:        | $\pm 0.09$ V secondary $\pm 5\%$ of setting       |  |
| Transient Overreach:       | ±5% of setting                                    |  |
| Synchronism-Check Elements |   |  |
| 25SC/25SM Maximum S        | lip Frequency for Controlled/Manual Close         |  |
| Setting Range:             | 0.005–0.500 Hz, 0.001-Hz steps                    |  |
| Pickup and Dropout:        | $\pm 0.002 \text{ Hz} \pm 2\%$ of setting         |  |
| 25AC Maximum Control       | led Close Angle                                   |  |
| Setting Range:             | $32 \cdot (25SC)$ to 90°, min = 1°, 0.1° steps    |  |
| Pickup and Dropout:        | $\pm 0.5^{\circ} \pm 5\%$ of setting              |  |
| 25AM Maximum Manual        | Close Angle                                       |  |
| Setting Range:             | 32 • (25SC) to 90°, min = 1°, $0.1^{\circ}$ steps |  |
| Pickup and Dropout:        | $\pm 0.5^{\circ} \pm 5\%$ of setting              |  |

#### **Current Unbalance Element**

46P Phase Current Unbalance Element

46P detects phase discordance when the protected breaker closes. For example, A-Phase is unbalanced if phase current is above the 50LD setting in one or more phases and:

< 1.35 cycles

IIA| < ( IIA| + IIB| + IIC| ) / 46UB setting where 46UB setting = 8, 16, 32, or 64.

Time to stabilize measurement because of transient conditions:

#### **Overpower Elements**

37OP Breaker Overpower Element

| Setting Range:                                | 0.10–3400.00 W secondary, 0.01-W steps<br>( $I_{NOM} = 5 A$ )<br>0.02–680.00 W secondary, 0.01-W steps<br>( $I_{NOM} = 1 A$ ) |
|---|---|
| Pickup Time:                                  | <2.10 cycles  |
| Dropout Time:                                 | <3.00 cycles  |
| Maximum Element<br>Error, Secondary<br>Units: | ±2.25 mW ±10.25%<br>(measured input power)<br>±2.63% (measured voltage)<br>±9.45% (measured current)                          |

#### **Breaker Resistor Thermal Elements**

| 26CF  | Close Resistor F                       | Failure Element   |  |
|-------|--|---|--|
| 26CP  | Close Resistor Pending Failure Element |   |  |
| 26TF  | Trip Resistor Failure Element          |   |  |
| 26TP  | Trip Resistor Pending Failure Element  |   |  |
| Setti | ng Range:                              | 0.010–1000.000 Joules secondary,<br>0.001 J-steps (I <sub>NOM</sub> = 5 A)<br>0.002–200.000 Joules secondary,<br>0.001 J-steps (I <sub>NOM</sub> = 1 A) |  |

Pickup error is based on 37OP element over time.

#### Settable Timers

| SYNCT Synchronizing Time Dropout (SYNCdo)  |  | ng Time Dropout (SYNCdo)  |
|--|--|---|
| Setting Range:   |  | 0.00-99999.00 cycles, 1/4-cycle steps   |
| Pickup Set   | ting:  | $\pm 0.25$ cycles or $\pm 0.25\%$ of setting  |
| 62TTFailure-to-Tr62FCFailure-to-Tr62T1General Purp62M2Maximum B62M3Maximum M   |  | ip Fault Current Trip Input Timer<br>ip Fault Current Failure Timer<br>oose Timer 1<br>us Clearing Time<br>IOD Operate Time                     |
| Setting Ra   | nge:   | 0.0-8191.0 cycles, 1/8-cycle steps  |
| Pickup Set   | ting:  | $\pm 0.25$ cycles or $\pm 0.25\%$ of setting  |
| SCT Synchronous Close Timer (CLSdo)   62LD Failure-to-Trip Load Current Failure Timer   62LP Failure-to-Trip Load Current Pending Failure T   62AF Failure of Breaker 52A Contact to Indicate Oper   Failure Timer Failure T |  | Close Timer (CLSdo)<br>ip Load Current Failure Timer<br>ip Load Current Pending Failure Timer<br>eaker 52A Contact to Indicate Operation<br>mer |
| 62AP   | Failure of Br<br>Pending F   | eaker 52A Contact to Indicate Operation<br>Failure Timer  |
| 62FF<br>62FP<br>62UC<br>62UP<br>62L2<br>62UF<br>62UF<br>62UF<br>62UP<br>62T3<br>62T4<br>62RT<br>62RC   | 2FFFlashover Failure Timer2FPFlashover Pending Failure Timer2UCPhase Discordance Close Input Pickup Timer2OPTrip and Close Resistor Heating Pickup Timer2L2Loss-of-Dielectric Timer2UFPhase Discordance Failure Timer2UPPhase Discordance Failure Timer2UPPhase Discordance Failure Timer2T3General Purpose Timer 32T4General Purpose Timer 42RTDelayed Trip Time2RCStaggered Close Time |   |
| Setting Ra   | nge:   | 0.00-16383.00 cycles, 1/4-cycle steps   |
| r ickup set  | ung.   | ±0.25 cycles of ±0.25% of setting   |

62ZCA A-Phase Zero-Crossing Controlled Close Timer 62ZCB B-Phase Zero-Crossing Controlled Close Timer 62ZCC C-Phase Zero-Crossing Controlled Close Timer 62PCA A-Phase Peak-Crossing Controlled Close Timer 62PCB B-Phase Peak-Crossing Controlled Close Timer C-Phase Peak-Crossing Controlled Close Timer 62PCC 62COApu A-Phase Controlled Open Timer 62COBpu B-Phase Controlled Open Timer 62COCpu C-Phase Controlled Open Timer 0.00-40.00 ms, 0.01-ms steps Setting Range: Pickup Setting: ±200 µsec 62VN Voltage Nulling Delay Timer 0.00-240.00 minutes, 0.01-min steps Setting Range: Pickup Setting: ±0.25 cycles or ±0.25% of setting **Fixed Timers** 62F1 Flashover Voltage Time Delayed Dropout Timer 5 cycles ±0.25 cycles 62F2 Load Current Pickup Timer (Flashover Logic) 5 cycles ±0.25 cycles 62F3 Trip or Close Dropout Timer (Flashover Logic) 6 cycles ±0.25 cycles 62M1 86BF Reset Signal Duration Timer 60 cycles ±0.125 cycles 62M4 86BF Reset Time Delay, MOD Logic Enabled 300 cycles ±0.125 cycles 62LT1 Loss-of-Dielectric Input Debounce Timer 60 cycles  $\pm 0.25$  cycles 62LT3 Loss-of-Dielectric Input Debounce Timer 60 cycles ±0.25 cycles MCT Manual Close Input Dropout Timer 2 cycles ±0.25 cycles SEN Synchronism Calculation Enable Pickup Timer 15 cycles ±0.25 cycles SS Slip Security Pickup Timer 4.5 cycles ±0.25 cycles Internal Logic Timers 62XZPB B-Phase Positive Zero-Crossing Delay Timer for X Side 62XZNB B-Phase Negative Zero-Crossing Delay Timer for X Side 0.33 cycles 62XZPC C-Phase Positive Zero-Crossing Delay Timer for X-Side 62XZNC C-Phase Negative Zero-Crossing Delay Timer for X-Side 0.66 cvcles 62YZPB B-Phase Positive Zero-Crossing Delay Timer for Y Side 62YZNB B-Phase Negative Zero-Crossing Delay Timer for Y Side 0.33 cycles 62YZPC C-Phase Positive Zero-Crossing Delay Timer for Y Side 62YZNC C-Phase Negative Zero-Crossing Delay Timer for Y Side 0.66 cycles 62T Trapped Charge Trip Input Dropout Timer 4 cycles 62V Trapped Charge Voltage Dropout Timer 7 cycles TCDpu Trapped Charge Detection Pickup Timer 1 cycle TCDdo Trapped Charge Detection Dropout Timer

12 cycles

|   | 62BALRM               | Breaker Alarm Dropout Timer  |  |  |
|---|-----------------------|--|--|--|
|   |                       | 60 cycles  |  |  |
|   | 62OI                  | Operation In   | put Dropout Timer for Breaker Alarms   |  |
|   |                       |  | 5 cycles   |  |
|   | 62BDNC                | BDNC Break   | er Alarm Close Inputs Pickup Timer   |  |
|   |                       |  | 3 seconds  |  |
|   | 62TWO                 | Trip Input D   | ropout Debounce Timer  |  |
|   |                       |  | 0.25 cycles  |  |
|   | T1A                   | Controlled O   | pen Trip Reset Timer   |  |
|   |                       |  | 10.00 cycles   |  |
|   | T2A                   | Controlled O   | pen Dropout Delay Timer  |  |
|   |                       |  | 0.75 cycles  |  |
|   | T3A                   | Controlled O   | pen Peak Delay Timer   |  |
|   |                       |  | 0.25 cycles  |  |
| M | etering               |  |  |  |
|   | VAX                   | A-Phase Volt   | age for the X-Side ac inputs   |  |
|   | VBX                   | B-Phase Volt   | age for the X-Side ac inputs   |  |
|   | VCX<br>VAV            | C-Phase Volt   | C-Phase Voltage for the X-Side ac inputs   |  |
|   | VBY                   | A-Phase Voltage for the Y-Side ac inputs<br>B-Phase Voltage for the Y-Side ac inputs |  |  |
|   | VCY                   | C-Phase Voltage for the Y-Side ac inputs   |  |  |
|   | Units:                |  | kilovolts (kV) primary   |  |
|   | Accuracy:             |  | ±0.67 V secondary  |  |
|   | IA                    | A-Phase current ac input   |  |  |
|   | IB                    | B-Phase current ac input   |  |  |
|   | IC III in a           | C-Phase curr   |  |  |
|   | Units:                |  | Amps (A) primary   |  |
|   | Accuracy:             |  | $\pm 0.05$ A secondary ( $I_{NOM} = 5$ A)<br>$\pm 0.01$ A secondary ( $I_{NOM} = 1$ A) |  |
|   | AMB                   | Ambient Ten  | nperature  |  |
|   |                       |  | -50° to +250°C   |  |
|   | Units:                |  | °C   |  |
|   | Accuracy:             |  | ±2°C   |  |
| M | ultiple Settii        | ng Groups  |  |  |
|   | SS1<br>SS2            | Setting group<br>Setting group   | o selection input 1<br>o selection input 2   |  |
|   | Number of<br>Groups:  | Setting  | 3  |  |
|   | Setting Gro<br>Delay: | oup Change   | TGR setting and as long as 3 seconds uncertainty                                       |  |
| _ |                       |  |  |  |

#### **Data Recording Specifications**

#### **Event Records**

| MER        | Event Report | Trigger                                   |
|------------|--------------|---|
| Pickup Acc | uracy:       | 0.000 to 0.125 cycles                     |
| Number of  | Events:      | 1200 ÷ LER setting (15, 30, or 60 cycles) |

|   | SER1<br>SER2<br>SER3                          | Sequential-Event-Recorder Trigger List 1<br>Sequential-Event-Recorder Trigger List 2<br>Sequential-Event-Recorder Trigger List 3 |                       |
|---|---|--|-----------------------|
|   | Pickup Ace                                    | curacy:  | 0.000 to 0.125 cycles |
|   | Number of<br>Elements                         | Trigger  | 24 per list, 72 total |
|   | Number of<br>Displaye                         | È Events<br>d:   | 512                   |
| E | Breaker Moni                                  | tor Reporting  |                       |
|   | Electrical Op<br>Units:                       | perate Time  | ms                    |
|   | Mechanical (<br>Units:                        | Operate Time   | ms                    |
|   | Energy Units                                  | 3:   | MJ, primary           |
|   | Current Unit                                  | s:   | A, primary            |
|   | Breaker Con                                   | tact Wear***:  | %                     |
|   | Number Of O<br>Displayed:                     | Operations   | 512                   |
|   | Other Relay Elements Determine Accuracy       |  |                       |
|   | Note: *** SEL-352-2 and SEL-352-3 Relays Only |  |                       |
|   |   |  |                       |

#### Serial Port Specifications

| Port 1: | EIA-485 with IRIG-B input  |
|---------|--|
| Port 2: | EIA-232 with IRIG-B input and +5 Vdc output.                             |
|         | Maximum total current draw on +5 Vdc supply through serial ports is 1 A. |
| Port 3: | EIA-232 with +5 Vdc output   |
| Port 4: | EIA-232  |

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